Curriculum Vitae

Personal Information	Name	Zbigniew Kulesza	Gender	Male	0	
	Academic Title	Associate Professor			20	
	College	Bialystok University of Technology				
	Discipline	automatic control and robotics				
	Email	z.kulesza@pb.edu.pl				
	Mail Add.	Wiejska 45D, 15-351 Bialystok, Poland				
Educational Background	Education 1990-1995, Faculty of Mechanical Engineering, Bialystok University of Technology, Poland 1992-1994, Inter-Department Pedagogic School, Bialystok University of Technology, Poland					
	Scientific degrees DSc 2014, Faculty of Mechanical Engineering and Robotics.					
	AGH University of Science and Technology, Poland, in the field of automatic control and robetice					
	PhD 2003, Faculty of Mechatronics, Warsaw University of Technology, Poland					
	in the field of machine design and maintenance, MSc, Eng. 1995, Faculty of Mechanical Engineering, Bialystok University of Technology, Poland, in the field of automation and robotization of industrial processes.					
Working Experience	Bialystok University of Technology, Bialystok, Poland 2019 - present Associate Professor, Department of Automatic Control and Robotics					
	Faculty of Electrical Engineering					
	2013-2019	Vice-Dean for Cooperation, Faculty of Mechanical Engineering, Vice-Head of Department, Department of Automatic Control and Robotics,				
	2015-2019	Faculty of Mechanical Engineering Associate Professor, Department of Automatic Control and Robotics,				
	2009-2012	Faculty of Mechanical Engineering Head of the Didactic Team for the Automatic Control and Robotics Studies,				
	2008-2009	Department of Automatic Control and Robotics, Faculty of Mechanical Engineering, Vice-Head of Department, Department of Automatic Control and Robotics, Faculty of Mechanical Engineering				
	2004-2015	Assistant Professor, Department of Automatic Control and Robotics,				
	1995-2004	Assistant, Department of Automatic Control and Robotics,				
	1994-1995	Faculty of Mechanical Engineering Trainee Assistant, Department of Automatic Control and Robotics,				
	Agrobusiness University	Faculty of Mechanical Engineering				
	1999-2009 Assistant, Assistant Professor, Department of Computer Science					
	Higher School of Computer Science in Business and Administration, Bialystok, Poland 1999-2005 Assistant, Assistant Professor, Department of Computer Science					
	ETOB Ltd., Bialystok, Poland 1995-2004 Database programmer, network and systems engineer					
Research Interests	dynamics and control of robot manipulators and mobile robots					
	rotordynamics					
	diagnostics of rotating machines					
	parametric and nonlinear vibrations					
	designing and programming of real time control systems					
	modeling and simulation of pneumatic brake systems					
Major Publications*	 Grądzki R., Lindstedt P. Bartoszewicz B., Kulesza Z., 2020, Assessment of rotor blades stationarity condition based on differences in phase shifts. Engineering Failure Analysis, 118, 1-12. Kulesza Z., Ołdziej D., 2020, Dynamic characteristics of a rope with a winder for powering UAV. In: 15th International Conference: Mechatronic Systems and Materials MSM'2020 / Kulesza Zbigniew [i in.] (red.), 					
	[3] 2020. [3] Gradzki R., vibration an	., Kulesza Z., Bartoszewicz B., 2019, Method of shaft crack detection based on squared gain of multitude. Nonlinear Dynamics, DOI: 10.1007/c11071-019-05221-0				
	[4] Gradzki R.,	Lindstedt P., Kulesza Z., Bartoszewicz B., 2018, Rotor blades diagnosis method based on in phase shift, Shock and Vibration 2018, article ID 0124607, DOI: 10.1155/0019/0124607				
	[5] Czajkowski	 In phase smits, smock and violation, 2018, afficie (D.9134607, DOI: 10.1155/2018/9134607. M., Bartoszewicz B., Kulesza Z., 2017, Modal analysis of rotor with a cracked shaft, Journal of price 10(1), 150–150. 				
	[6] Uszynski S.	ering, 19(1), 150-159. , Ambroziak L., 2018, Kondratiuk M., Kulesza Z., Air consumption analysis in compressed air				

	 powered vehicles, In: Proceedings of the 13rd International Conference on Methods and Models in Automation and Robotics, MMAR'2018, Miedzyzdroje, Poland, August 27-30. [7] Kulesza Z., Trochimczuk R., 2017, Dynamics of multibody surgical robotic single incision laparoscopic surgery tool, In: Proceedings of the 23rd International Conference Engineering Mechanics'2017, Svratka, Czech Republic, May 15-18, 2017. [8] Kulesza Z., Sawicki J. T., 2016, Parametrically induced damping in a cracked rotor, ASME Journal of Gas Turbines and Power, 139(1), 012505. [9] Tomczyk L., Kulesza Z., 2016, A method of prioritizing victims of a mass casualty event for managing medical rescue operations, Control and Cybernetics, 45(3), 355-369. [10] Kulesza Z., Huscio T., 2016, Influence of load conditions in membrane spring-loaded cylinder on dynamic characteristics of pneumatic brake system, In: Proceedings of the 15th International Scientific Conference: Engineering for Rural Development, Jelgava, Latvia, May 25-27. [11] Kulesza Z., Sawicki J. T., 2016, Parametrically induced damping in a cracked rotor, In: Proceedings of ASME Turbo Expo 2016: Turbomachinery Technical Conference and Exposition GT2016, Seoul, South Korea, June 13-17. 		
Research Projects*	 2017-2020 Head of the Steering Committee and Research Expert at the National Center for Research and Development of Poland (NCBR) grant: "Autonomous vessel with air look", Consortium of: Bialystok University of Technology, Foundation for Safety of Navigation and Environment Protection, Sup4Nav Ltd., UpLogic Ltd. 2020-2023 Director of the University Project No WZ/WE-IA/4/2020 on "Dynamics, control and autonomy of service and industrial robots", Department of Automatic Control and Robotics, Faculty of Electrical Engineering, Bialystok University of Technology. 		
Professional Membership	American Society of Mechanical Engineers, ASME, since 2012. Association of Polish Mechanical Engineers and Technicians, SIMP, since 2008. Polish Society of Theoretical and Applied Electrical Engineering, PTETiS, since 2020.		
Potential Research Projects**	New diagnostic methods for rotating machines failure detection Dynamics and control of manipulators and mobile robots Real time control systems for robotics		

* Please list achievements of recent 5 years

** This CV is intended to match Chinese and Polish Scientists within SPUC member universities, and Potential Research Projects is intended to apply for

Sino-Polish or EU scientific cooperation projects.